

## Addition of 3 angular momenta

Let  $\vec{J}_1, \vec{J}_2$ , and  $\vec{J}_3$  be three angular momentum operators, and let  $\vec{J} = \vec{J}_1 + \vec{J}_2 + \vec{J}_3$ .

Common eigenvectors of  $J^2$  and  $J_z$  are characterized by the quantum numbers  $j$  and  $m$ .

Let the quantum numbers  $j_1, j_2$ , and  $j_3$  be fixed (for example, consider 3 spin  $\frac{1}{2}$  particles) and consider the subspace  $E(j_1, j_2, j_3, j, m)$  of all states characterized by fixed values of  $j_1, j_2, j_3, j$ , and  $m$ .

$J_1^2, J_2^2, J_3^2, J^2$  and  $J_z$  do not form a C.S.C.O. for  $E(j_1, j_2, j_3, j, m)$ .

We need an additional observable to form a C.S.C.O.

$$\textcircled{1} \begin{aligned} \vec{J}_1 + \vec{J}_2 &= \vec{J}_{12} \\ \vec{J}_2 + \vec{J}_3 &= \vec{J}' \end{aligned}$$

$$\textcircled{2} \begin{aligned} \vec{J}_1 + \vec{J}_3 &= \vec{J}_{13} \\ \vec{J}_3 + \vec{J}_2 &= \vec{J}'' \end{aligned}$$

$$\textcircled{3} \begin{aligned} \vec{J}_1 + \vec{J}_3 &= \vec{J}_{13} \\ \vec{J}_3 + \vec{J}_2 &= \vec{J}'' \end{aligned}$$

Choosing this additional observable means choosing an angular momentum coupling scheme.

The common eigenvectors of  $J_1^2, J_2^2, J_3^2, J^2$  and  $J_z$  and this additional observable form a basis for  $E(j_1, j_2, j_3, j, m)$ .

Let this additional observable be  $J_{12}^2$  ( $J_{12} = \vec{J}_1 + \vec{J}_2$ ). Then the basis vectors are  $\{ |j_1, j_2, [j_{12}], j_3, j, m\rangle \}$ . (We do not have to write  $|j_1, j_2, [j_{12}], j_3, j, m\rangle$  because all vectors in  $E(j_1, j_2, j_3, j, m)$  have quantum number  $j$  and  $m$ .)

Similarly, if the additional observable is  $J_{13}^2$  then the basis vectors are  $\{ |j_1, j_3, [j_{13}], j_2, j, m\rangle \}$ , and if the additional observable is  $J_{23}^2$  then the basis vectors are  $\{ |j_2, j_3, [j_{23}], j_1, j, m\rangle \}$ .

We can transform from one coupling scheme to another coupling scheme.

For example

$$|j_1, j_2, j_3, [j_{23}]\rangle = \sum_{j_{12}} |j_1, j_2, [j_{12}], j_3, j, m\rangle \underbrace{\langle j_1, j_2, [j_{12}], j_3, j, m | j_1, j_2, j_3, [j_{23}]\rangle}_{[j_{12}, j_{23}]^{1/2} W(j_1, j_2, j_3, j, j_2, j_3)}$$

defines the Racah W-coefficient. Here  $[j_1, j_2, \dots] = (2j_1+1)(2j_2+1)\dots$

Similarly,

$$|j_1 j_3 [j_{13}] ; j_2 \rangle = \sum_{j_{12}} |j_1 j_2 [j_{12}] ; j_2 \rangle \underbrace{\langle j_1 j_2 [j_{12}] j_3 | j_1 j_3 [j_{13}] ; j_2 \rangle}_{[j_{12} j_{13}]^{1/2} W(j_{12} j_3 j_2 j_{13} ; j_1 j_2)}$$

Definition of the Racah W-coefficients:

$$\langle j_1 j_2 [j' j_3] j_1 m_1 j_2 m_2 [j'' j_1] ; j m \rangle = \frac{1}{\sqrt{(2j'+1)(2j''+1)}} W(j_1 j_2 j_3 ; j' j'')$$

$$\langle j_1 j_2 [j' j_3] j_1 m_1 j_1 j_3 [j'' j_2] ; j m \rangle = \frac{1}{\sqrt{(2j'+1)(2j''+1)}} W(j' j_3 j_2 j'' ; j_1 j_1)$$

We can express the Racah W-coefficients in terms of the Clebsch-Gordon coefficients.

We may write

$$\begin{aligned} |j_1 j_2 j_3 [j_{123}] \rangle &= \sum_{m_1 m_2 m_3} |j_1 m_1 j_2 m_2 j_3 m_3 \rangle \langle j_1 m_1 j_2 m_2 j_3 m_3 | j_1 j_2 j_3 [j_{123}] \rangle \\ &= \sum_{\substack{m_1 m_2 m_3 \\ m_{12}}} |j_1 m_1 j_2 m_2 j_3 m_3 \rangle \langle j_1 m_1 j_2 m_2 j_3 m_3 | j_1 m_1 j_2 m_{12} \rangle \langle j_1 m_1 j_2 m_{12} j_3 m_3 | j_1 j_2 j_3 [j_{123}] \rangle \end{aligned}$$

But we also have

$$\begin{aligned} |j_1 j_2 j_3 [j_{123}] \rangle &= \sum_{j_{12}} \underbrace{|j_1 j_2 [j_{12}] ; j_3 \rangle}_{[j_{12} j_{13}]^{1/2} W(j_1 j_2 j_3 ; j_{12} j_{13})} \\ &\quad \sum_{\substack{m_1 m_2 m_3 \\ m_{12}}} |j_1 m_1 j_2 m_2 j_3 m_3 \rangle \langle j_1 m_1 j_2 m_2 j_3 m_3 | j_{12} m_{12} j_3 m_3 \rangle \langle j_{12} m_{12} j_3 m_3 | j_1 j_2 [j_{12}] ; j_3 \rangle \end{aligned}$$

The vectors  $|j_1 m_1 j_2 m_2 j_3 m_3 \rangle$  with different  $m_1, m_2$ , or  $m_3$  are orthogonal. We can therefore equate the coefficients with equal  $m_1, m_2$  and  $m_3$ .

$$\sum_{m_{12}} \underbrace{\langle j_1 m_1 j_2 m_2 j_3 m_3 | j_1 m_1 j_2 m_{12} \rangle}_{\langle j_2 m_2 j_3 m_3 | j_{12} m_{12} \rangle} \underbrace{\langle j_1 m_1 j_2 m_{12} j_3 m_3 | j_1 j_2 j_3 [j_{123}] \rangle}_{\langle j_1 m_1 j_2 m_{12} j_3 m_3 | j_1 m_1 j_2 m_{12} \rangle} = C_{m_1 m_2 m_3}^{j_{123}} \langle j_1 m_1 j_2 m_{12} j_3 m_3 | j_1 m_1 j_2 m_{12} \rangle = C_{m_1 m_2 m_3}^j$$

$$\begin{aligned} &= \sum_{j_{12}} [j_{12} j_{13}]^{1/2} W(j_1 j_2 j_3 ; j_{12} j_{13}) \sum_{m_{12}} \underbrace{\langle j_1 m_1 j_2 m_2 j_3 m_3 | j_{12} m_{12} j_3 m_3 \rangle}_{\langle j_1 m_1 j_2 m_2 | j_{12} m_{12} \rangle} \underbrace{\langle j_{12} m_{12} j_3 m_3 | j_1 j_2 [j_{12}] ; j_3 \rangle}_{\langle j_{12} m_{12} j_3 m_3 | j_1 m_1 j_2 m_{12} \rangle} = C_{m_1 m_2 m_3}^j \end{aligned}$$

Now we can use the orthogonality of the CG coefficients:

$$\sum_{m_1, m_2} \langle j_1 j_2 j' m' | j_1 j_2 m_1 m_2 \rangle \langle j_1 j_2 m_1 m_2 | j_1 j_2 j m \rangle = \sum_{m_1, m_2} C_{m_1 m_2}^{j'} C_{m_1 m_2}^j = \delta_{j' j} \delta_{m m'}$$

and

$$\sum_{j, m} \langle j_1 j_2 j' m' | j_1 j_2 j m \rangle \langle j_1 j_2 j m | j_1 j_2 j' m' \rangle = \sum_{j, m} C_{m_1 m_2}^{j'} C_{m_1 m_2}^j = \delta_{m_1' m_1} \delta_{m_2' m_2}$$

(The CG coefficients are real.)

Therefore

$$\begin{aligned} & \sum_{\substack{m_1, m_2, m_3 \\ m_{23}, m_{12}}} C_{m_2 m_3}^{j_3} C_{m_1 m_{23}}^j C_{m_1 m_2}^{j_1} C_{m_2 m_3}^j \\ &= \sum_{\substack{m_1, m_2, m_3 \\ j_{12}, m_{12}}} [j_{12}, j_{23}]^{1/2} W(j_1 j_2 j_3, j_{12} j_{23}) \underbrace{C_{m_1 m_2}^{j_1} C_{m_1 m_2}^{j_2}}_{\text{The sum yields } \delta_{j_1 j_2}} \underbrace{C_{m_2 m_3}^j C_{m_2 m_3}^j}_{\text{The sum yields } 1} \\ &= [j_{12}, j_{23}]^{1/2} W(j_1 j_2 j_3; j_{12} j_{23}). \end{aligned}$$

The Racah coefficient is independent of the values of  $m_1, m_2, m_3, m_{12},$  and  $m_{23}$  and is a function of its six arguments only.

The W-coefficients can be expressed in terms of the 6-j symbols.

$$W(j_1 j_2 l_1 l_2; j_3 l_3) = (-1)^{j_1 + j_2 + l_1 + l_2} \begin{Bmatrix} j_1 & j_2 & j_3 \\ l_1 & l_2 & l_3 \end{Bmatrix}$$

6-j symbol calculators can be found on the WWW.

Example:

For the transition from the scheme

$$\vec{l}_1 + \vec{l}_2 = \vec{L}^1, \quad \vec{s}_1 + \vec{s}_2 = \vec{S}^1, \quad \vec{L}^1 + \vec{L}_3 = \vec{L}, \quad \vec{S}^1 + \vec{S}_3 = \vec{S}, \quad \text{to the scheme}$$

$$\vec{l}_1 + \vec{l}_3 = \vec{L}^2, \quad \vec{s}_2 + \vec{s}_3 = \vec{S}^2, \quad \vec{L}^2 + \vec{L}^1 = \vec{L}, \quad \vec{S}^2 + \vec{S}^1 = \vec{S} \quad \text{we have}$$

$$\langle l_1 s_1, l_2 s_2 [L^1 S^1]; l_3 s_3; LS | l_1 s_1, l_2 s_2, l_3 s_3 [L^2 S^2]; LS \rangle = [L^1 L^2 S^1 S^2]^{1/2} W(l_1 l_2 L l_3; L^1 L^2) W(s_1 s_2 S s_3; S^1 S^2).$$

## Addition of 4 angular momenta

For the full description of a state, it is necessary to give the quantum numbers  $j$  and  $m$ , as well as the angular momenta of two-particle or three-particle subsystems.

Consider the subspace  $E(j_1 j_2 j_3 j_4 j m)$ .

A state in this subspace may be described by the quantum numbers

$j_1 j_2 [j_1 j_2] j_3 [j_1 j_2 j_3] j_4 j m$  or  $j_1 j_2 j_3 [j_1 j_2 j_3] j_4 j m$  or  $j_1 j_2 [j_1 j_2] j_3 j_4 [j_1 j_2 j_3] j m$  or  $j_1 j_3 [j_1 j_3] j_2 j_4 [j_1 j_3 j_2] j m$ , and so on.

Consider, for example, the transformation from the coupling scheme  $j_1 j_2 [j_1 j_2] j_3 j_4 [j_1 j_2 j_3] j m$  to the scheme  $j_1 j_3 [j_1 j_3] j_2 j_4 [j_1 j_3 j_2] j m$ .

$$|j_1 j_2 j_3 j_4 j m\rangle = \sum_{j_1 j_3 j_2 j_4} |j_1 j_3 j_2 j_4 j m\rangle \underbrace{\langle j_1 j_3 j_2 j_4 j m | j_1 j_2 j_3 j_4 j m \rangle}_{\text{recoupling coefficient } \Delta}.$$

The recoupling coefficient  $\Delta$  can be written in terms of the Racah  $W$ -coefficients or the 6- $j$  symbols.

$$\Delta = [j_1 j_2 j_3 j_4 j_1 j_3 j_2 j_4]^{1/2} \sum_{j'} (-1)^{2j'} (2j'+1) \begin{Bmatrix} j_1 j_2 j_2 \\ j_3 j_1 j' \end{Bmatrix} \begin{Bmatrix} j_3 j_4 j_3 \\ j_2 j' j_2 \end{Bmatrix} \begin{Bmatrix} j_1 j_2 j_4 \\ j' j_1 j_3 \end{Bmatrix}.$$

We define the 9- $j$  symbol as

$$\begin{Bmatrix} j_1 j_2 j_2 \\ j_3 j_4 j_3 \\ j_1 j_3 j_4 \end{Bmatrix} = \sum_{j'} (-1)^{2j'} (2j'+1) \begin{Bmatrix} j_1 j_2 j_2 \\ j_3 j_1 j' \end{Bmatrix} \begin{Bmatrix} j_3 j_4 j_3 \\ j_2 j' j_2 \end{Bmatrix} \begin{Bmatrix} j_1 j_3 j_4 \\ j' j_1 j_3 \end{Bmatrix}.$$

$$\text{Then } \Delta = [j_1 j_2 j_3 j_4 j_1 j_3 j_2 j_4]^{1/2} \begin{Bmatrix} j_1 j_2 j_2 \\ j_3 j_4 j_3 \\ j_1 j_3 j_4 \end{Bmatrix}.$$

9- $j$  symbol calculators can be found on the WWW.